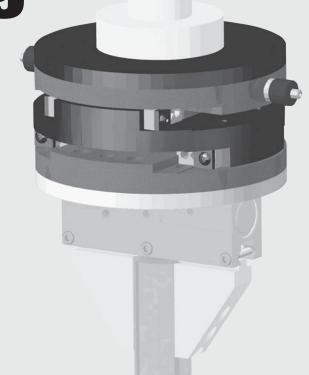
Lateral Compliance Device – Pneumatic Centering

Robotic applications:

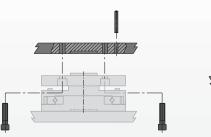
For inserting components that may be laterally misaligned with respect to mating parts. Reduces part jamming which could transmit excessive forces to the robot. Robot and tool side mounting patterns are made to DIN robot mounting standards.

Automation applications:

For insertion applications where part positioning may be less than precise. Compliance in lateral directions allows this device to compensate for part placing inaccuracies. Reduces jamming of mating components.



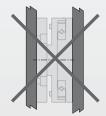
Mounting Information:



Robot side has counter bored holes for mounting with a dowel hole and raised boss for location



The tool side has tapped holes for mounting and a pilot hole and dowel hole for positioning



Not recommended in horizontal axis applications where the weight attached to the tool side can deflect the device

Technical Specifications:

Pneumatic Specifications Pressure Operating Range Cylinder Type Dynamic Seals

Valve Required to Operate

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

40-100 psi 3-7 bar **Double Acting Buna-N** 4-way, 2-position

Imperial

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range

Buna-N Seals (standard)

-20°~180° F

-30°~80° C

Metric

Maintenance Specifications†

Expected Life Normal Application w/ Preventative Maintenance

5 million cycles 10+ million cycles*

Application Restrictions

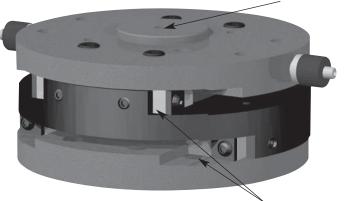
- Dirty or gritty environments
- Machining operations generating chips
- Environments with loose particulate
- *Addition of lubrication will greatly increase service life † See Maintenance Section

Product Features

Hard Coat Anodize Anodized aluminum components

Locking Cylinder

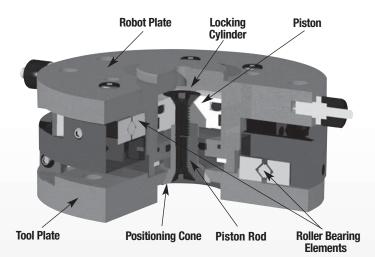
Locking cylinder creates a rigid connection between robot and tool side

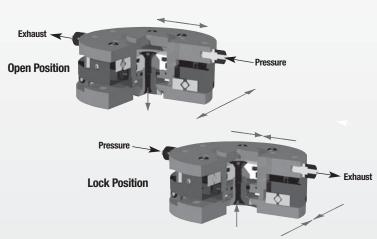


Crossed Roller Bearing

Crossed roller bearings eliminate side forces generated by placing misaligned components

Operating Principle





- . The two halves of this device are connected by two pairs of crossed roller bearing slides that are perpendicular to one another.
- In the unlocked position, relative motion can occur independently between the two halves in both the X & Y directions.
- In the locked position, the tool half is brought back on center with respect to the robot half with the use of cone centering which is actuated by the built in air cylinder.

Style-KA Lateral Alignment

Size -80R

Style: Max. Payload: Max. Misalignment: 0.08 in. 2mm Weight: 1.10 lb 0.50 Kg

2 lb 1 Kg



See **6.72**

Style-KA Lateral Alignment

Size -100

Style:KA-100Max. Payload:5 lb2.5 kgMax. Misalignment:0.08 in.2mm Weight:

1.80 lb 0.82 Kg

See **6.73**

Style-KA Lateral Alignment

Size -125

Style: Max. Payload:

 Max. Payload:
 10 lb
 5 Kg

 Max. Misalignment:
 0.12 in.
 3.00mm

 Weight:
 4.4 lb
 2.0 Kg



See **6.74**

Style-KA Lateral Alignment

Size -160

Style: Max. Payload: Max. Misalignment: Weight:

KA-160 lb 11 Kg in. 4mm 25 lb 0.15 in. 7.0 lb



See **6.75**

Style-KA Lateral Alignment

Size -200

 Style:
 KA-2UU

 Max. Payload:
 90 lb
 40 Kg

 Max. Misalignment:
 0.47 in.
 12 mm

 16.5 lb
 7.5 Kg



See **6.76**

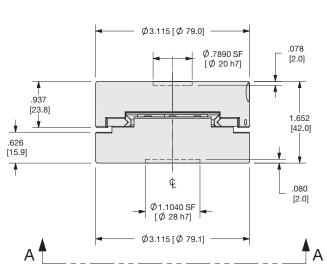
Style-KA Lateral Alignment

Size -300

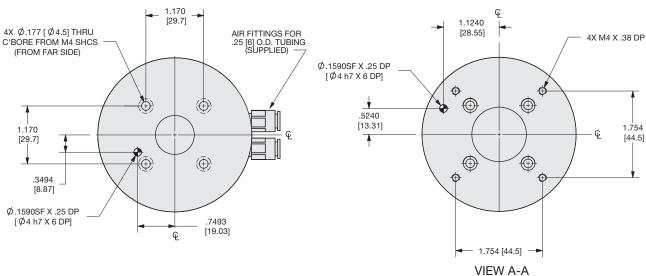
Style: Max. Payload:

200 Kg 440 lb Max. Misalignment: 0.98 in. Weight: 115 lb

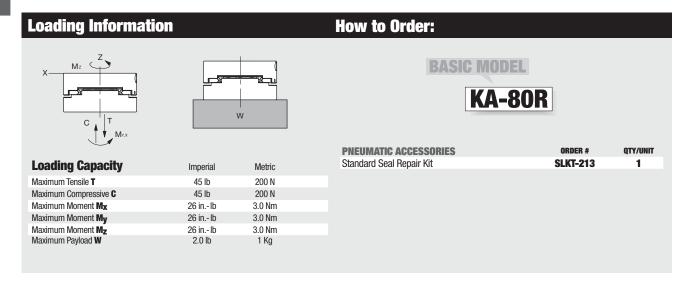
See **6.77**



Specifications KA-80R Maximum Payload. 1 Kg 2 lbs Misalignment Capability ±0.08 in. ±2 mm 0.50 Kg 1.1 lb Pressure Range (locked cylinder) 40-100 psi 3-7 bar -30°~80° C Temperature Range.. -20°~180° F 133 N 30 lbs Locking Force @ 80 PSI [5.5 bar]..... ±0.03 mm Valve required to actuate..... 4-way, 2-position

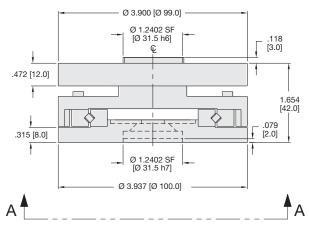


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Dimensions are projection Third Angle Projection All Dowel Holes are SF (Slip Rt). Locational Tolerance ±.0005" or [±.013mm] All Dowel Holes are SF (Slip Rt). Course Pitch Course Pitch 0.000 = ±.015 0.0000 = ±.005 0.0000 = ±.005 0.0000 = ±.005 0.0000 = ±.005 0.0000 = ±.005 0.0000 = ±.005 0.0000 = ±.005

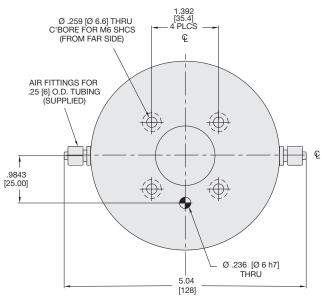


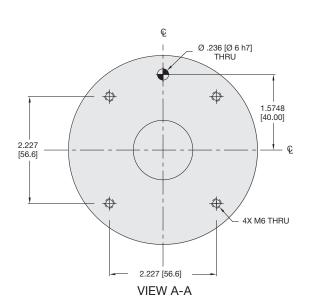


LATERAL ALIGNMENT KA-100 PNEUMATIC CENTERING SERIES



Specifications	KA-100		
Maximum Payload	5 lbs	2.5 Kg	
Misalignment Capability	±0.08 in.	±2 mm	
Weight	1.80 lb	0.82 Kg	
Pressure Range (locked cylinder)	40-100 psi	3-7 bar	
Temperature Range	-20°~180° F	-30°~80° C	
Locking Force @ 80 PSI [5.5 bar]	70 lbs	311 N	
Repeatability	±0.001 in.	±0.03 mm	
Valve required to actuate	4-way, 2-position		





- UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

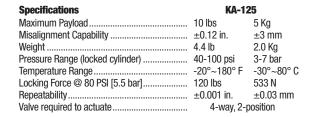
All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

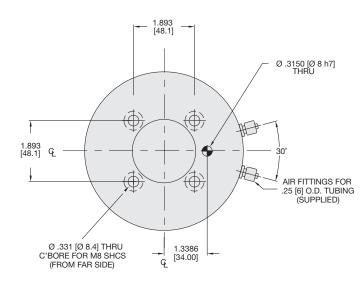
Metric Threads Course Pitch Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

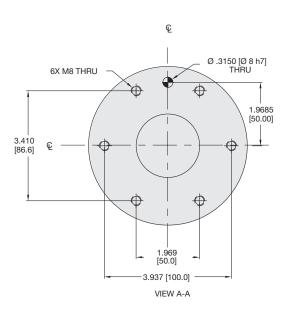
Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Loading Information How to Order: BASIC MODEL KA-100 ·--- \$ W C **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Standard Seal Repair Kit **SLKT-132** 1 **Loading Capacity** Imperial Metric Maximum Tensile **T** 90 lb 400 N Maximum Compressive C 90 lb 400 N 30.0 Nm Maximum Moment Mx 265 in.- lb 30.0 Nm Maximum Moment My 265 in.-lb 30.0 Nm Maximum Moment $\mathbf{M}_{\mathbf{Z}}$ 265 in.-lb Maximum Payload **W** 5 lb 2.5 Kg

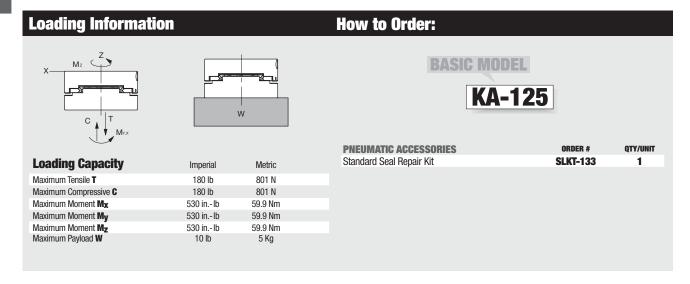
<u> </u>			[Ø 125.0] 685 SF 0 h6]		.118 [3.0]
.472 [12.0]					† †
.354 [9.0]		Ø 1.96 — [Ø 50	•	\[\frac{1}{2} \]	1.980 .157 [50.3]
A					A





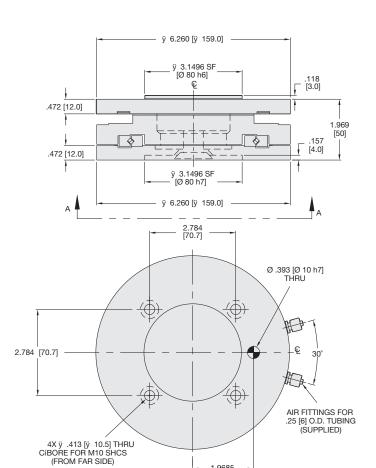


UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW Dimensions are symmetrical about centerline Third Angle Projection Locational Tolerance \pm .0005° or $[\pm$.013mm] All Dowel Holes are SF (Slip Fit). Locational Tolerance \pm .0005° or $[\pm$.013mm] Metric Threads Course Pitch 0.000 \pm .000 \pm .010 \pm .013





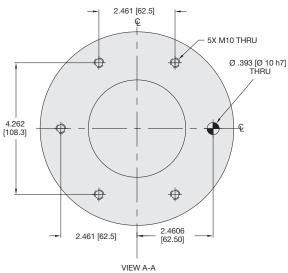
LATERAL ALIGNMENT KA-160 PNEUMATIC CENTERING SERIES



1.9685 [50.00]

Œ

Specifications	KA-160		
Maximum Payload	25 lbs	11 Kg	
Misalignment Capability	±0.15 in.	±4 mm	
Weight	7.0 lb	3.2 Kg	
Pressure Range (locked cylinder)	40-100 psi	3-7 bar	
Temperature Range	-20°~180° F	-30°~80° C	
Locking Force @ 80 PSI [5.5 bar]	120 lbs	533 N	
Repeatability	±0.001 in.	±0.03 mm	
Valve required to actuate	4-way, 2-position		



UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

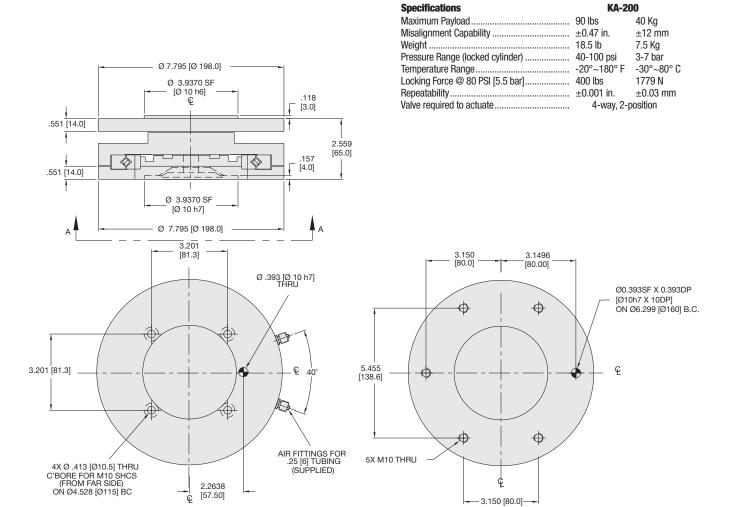
Third Angle Projection

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Metric Threads Course Pitch Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

Loading Information How to Order: BASIC MODEL KA-160 ·--- \$ W C **PNEUMATIC ACCESSORIES** ORDER # QTY/UNIT Standard Seal Repair Kit **SLKT-134** 1 **Loading Capacity** Imperial Metric Maximum Tensile **T** 225 lb 1001 N Maximum Compressive C 225 lb 1001 N Maximum Moment Mx 885 in.-lb 100.0 Nm 100.0 Nm Maximum Moment My 885 in.-lb 100.0 Nm Maximum Moment $\mathbf{M}_{\mathbf{Z}}$ 885 in.-lb Maximum Payload **W** 25 lb 11 Kg



VIEW A-A

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

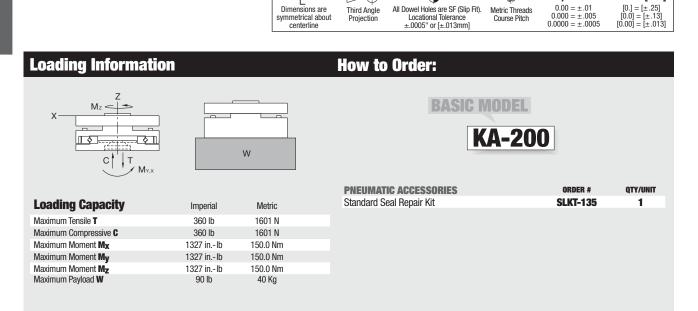
0

Metric Threads

Course Pitch

Imperial in.

Metric [mm]



 $\triangleright \oplus$

Third Angle

Projection

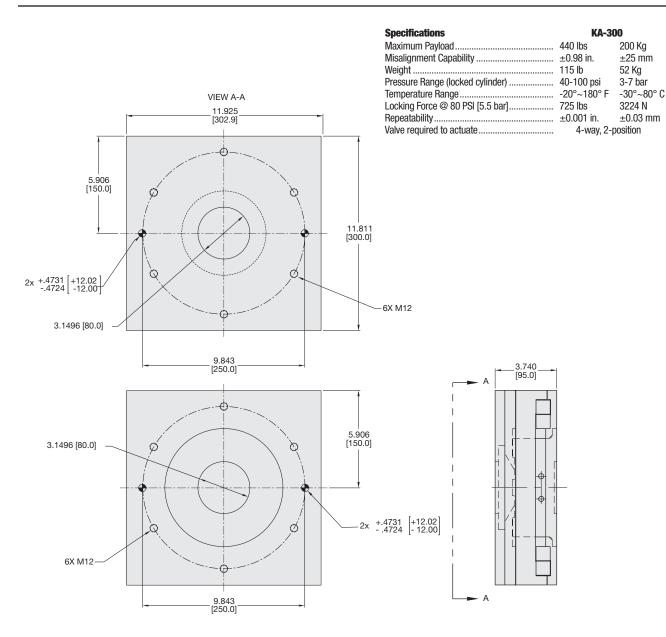
q

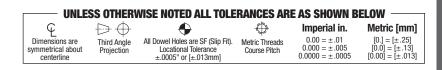
Dimensions are symmetrical about

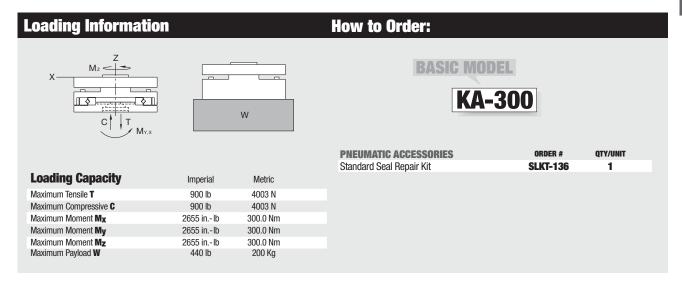
centerline



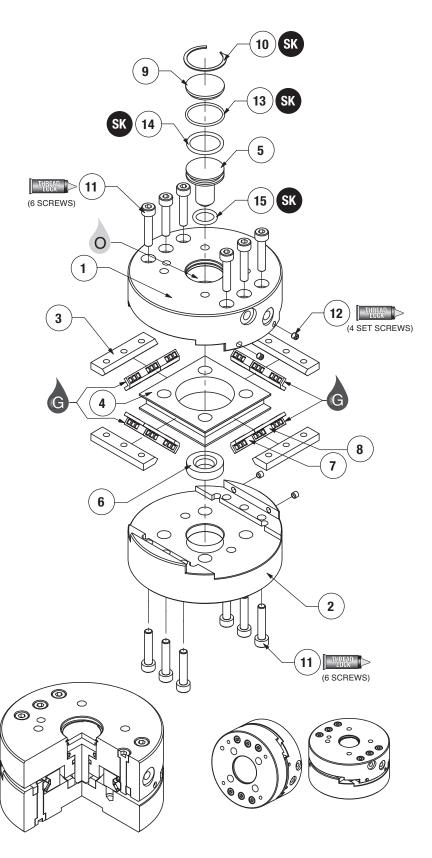
LATERAL ALIGNMENT KA-300 PNEUMATIC CENTERING SERIES











01 1 Robot Half 02 1 Tool Half 03 4 Way 04 1 Center Rail	
03 4 Way	_
	_
04 1 Center Bail	
05 1 Piston	_
06 1 Bushing	_
07 4 Roller Cage Half	
08 4 Roller Cage Full	_
09 1 Cap	_
10 1 Retaining Ring	
11 12 Socket Head Screw	_
12 4 Set Screw	_
13 1 0-Ring	
14 1 0-Ring	
15 1 0-Ring	_

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Preload Adjustment

- 1) Loosen the six socket head cap screws on the robot half (1) about 1/2 turn.
- Seat the way (3) that is furthest from the preload set screws (4) in position and using loctite on the threads, tighten those three screws to fasten the way in place.
- 3) Evenly advance the two preload set screws to a point where there is no play in the robot half.
- 4) Using loctite on the threads, tighten the remaining three screws to fasten the way (3) in place. **NOTE:**There is a possibility that when the second set of screws are tightened, the preload will increase if this happens, loosen the three screws again and back off slightly and evenly on the two preload adjustment set screws.
- 5) Follow 1 thru 4 again to adjust the preload for the tool half (2).
- 6) Be sure that the bearings glide freely if the unit becomes choppy then the preload might be too tight.
- 7) As a check to see that the preload has been set properly, you should be able to push on the end of one of the nylon bearing cages with about 3 pounds, and that half will move without the bearing skidding.











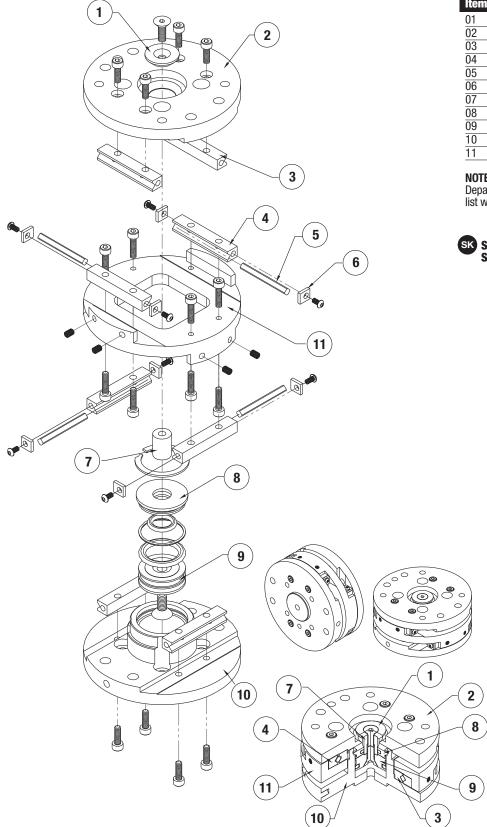






6.79





Item	Qty	Name
01	1	Centering Cone
02	1	Top Plate
03	4	Rail,Fixed
04	4	Rail, Moveable
05	4	Bearings
06	8	Stop
07	1	Shaft
80	1	Cap
09	1	Piston
10	1	Bottom Plate
11	1	Center Plate

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

SK Seal Repair Kit Order #'s See Product Data Sheets













